Applying High Performance Computing to Multi-Area Stochastic Unit Commitment IBM Research

Anthony Papavasiliou, Department of Mathematical Engineering, CORE, UCL Shmuel Oren, IEOR Department, UC Berkeley

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Motivation and Research Objective

- Increased computational burden in power systems operations due to:
 - renewable penetration and
 - demand response integration
- Potential applications of distributed computation:
 - Stochastic optimization
 - Robust optimization
 - Topology control, system expansion planning
 - Optimization of storage (deferrable loads/demand response, hydro-thermal scheduling)
- Want to quantify sensitivity of:
 - unit commitment policy
 - duality gaps
 - cost performance

on number of scenarios.

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Parallel Computing Literature in Power Systems

- Monticelli et al. (1987): Benders decomposition algorithm for SCOPF
- Pereira et al. (1990): Various applications of parallelization including SCOPF, composite (generator, transmission line) reliability, hydrothermal scheduling
- Falcao (1997): Survey of HPC applications in power systems
- Kim, Baldick (1997): Distributed OPF
- Bakirtzis, Biskas (2003) and Biskas et al. (2005): Distributed OPF

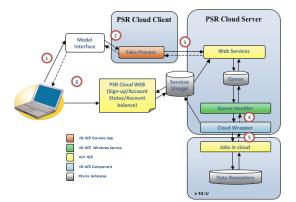
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PSR Cloud

Industry practice for hydrothermal scheduling

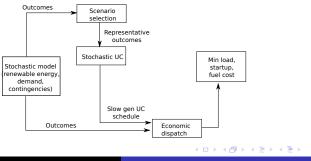


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Lagrangian Decomposition Scenario Selection

Full Model

- Application: stochastic unit commitment for large-scale renewable energy integration
- Two-stage model representing DA market (first stage) followed by RT market (second stage)



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Lagrangian Decomposition Scenario Selection

Unit Commitment Model

- Domain \mathcal{D} represents min up/down times, ramping rates, thermal limits of lines, reserve requirements
- Generator set partitioned between fast (G_f) and slow (G_s) generators

$$(UC): \min \sum_{g \in G} \sum_{t \in T} (K_g u_{gt} + S_g v_{gt} + C_g p_{gt})$$

s.t.
$$\sum_{g \in G_n} p_{gt} = D_{nt}$$

$$P_g^- u_{gt} \le p_{gt} \le P_g^+ u_{gt}$$

$$e_{lt} = B_l(\theta_{nt} - \theta_{mt})$$

(**p**, **e**, **u**, **v**) $\in \mathcal{D}$

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Lagrangian Decomposition Scenario Selection

Stochastic Unit Commitment Model

$$(SUC): \min \sum_{g \in G} \sum_{s \in S} \sum_{t \in T} \pi_s (K_g u_{gst} + S_g v_{gst} + C_g p_{gst})$$

$$s.t. \sum_{g \in G_n} p_{gst} = D_{nst},$$

$$P_{gs}^- u_{gst} \le p_{gst} \le P_{gs}^+ u_{gst}$$

$$e_{lst} = B_{ls}(\theta_{nst} - \theta_{mst})$$

$$(\mathbf{p}, \mathbf{e}, \mathbf{u}, \mathbf{v}) \in \mathcal{D}_s$$

$$u_{gst} = w_{gt}, v_{gst} = z_{gt}, g \in G_s$$

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Lagrangian Decomposition Algorithm

- Past work: (Takriti et al., 1996), (Carpentier et al., 1996), (Nowak and Römisch, 2000), (Shiina and Birge, 2004)
- Key idea: relax non-anticipativity constraints on both unit commitment and startup variables
 - Balance size of subproblems
 - Obtain lower and upper bounds at each iteration

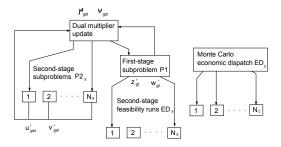
Lagrangian:

$$\mathcal{L} = \sum_{g \in G} \sum_{s \in S} \sum_{t \in T} \pi_s (K_g u_{gst} + S_g v_{gst} + C_g \rho_{gst}) \\ + \sum_{g \in G_s} \sum_{s \in S} \sum_{t \in T} \pi_s (\mu_{gst} (u_{gst} - w_{gt}) + \nu_{gst} (v_{gst} - z_{gt}))$$

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Lagrangian Decomposition Scenario Selection

Parallelization



- Lawrence Livermore National Laboratory Hera cluster: 13,824 cores on 864 nodes, 2.3 Ghz, 32 GB/node
- MPI calling on CPLEX Java callable library

Introduction Model Scenario Selection Results

Scenario Selection

- Past work: (Gröwe-Kuska et al., 2002), (Dupacova et al., 2003), (Heitsch and Römisch, 2003), (Morales et al., 2009)
- Scenario selection algorithm inspired by importance sampling
 - **O** Generate a sample set $\Omega_S \subset \Omega$, where $M = |\Omega_S|$ is adequately large. Calculate the cost $C_D(\omega)$ of each sample $\omega \in \Omega_S$ against the best deterministic unit commitment

policy and the average cost $\bar{C} = \sum_{i=1}^{M} \frac{C_D(\omega_i)}{M}$.

Choose N scenarios from Ω_S , where the probability of picking a scenario ω is $C_D(\omega)/(M\bar{C})$. 3 Set $\pi_s = C_D(\omega)^{-1}$ for all $\omega^s \in \hat{\Omega}$.

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Lagrangian Decomposition Scenario Selection

Wind Production Model

- Relevant literature: (Brown et al, 1984), (Torres et al., 2005), (Morales et al, 2010)
- Calibration steps

Remove systematic effects:

$$y_{kt}^{S} = rac{y_{kt} - \hat{\mu}_{kmt}}{\hat{\sigma}_{kmt}}.$$



Transform data to obtain a Gaussian distribution:

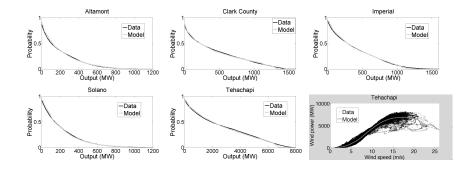
$$y_{kt}^{GS} = N^{-1}(\hat{F}_k(y_{kt}^S)).$$

Sestimate the autoregressive parameters φ_{kj} and covariance matrix Σ̂ using Yule-Walker equations.

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Lagrangian Decomposition Scenario Selection

Data Fit

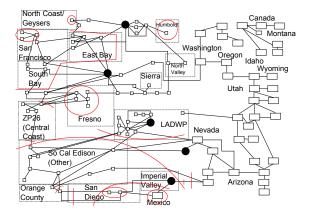


A. Papavasiliou Parallel Stochastic Unit Commitment

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WECC Model



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Unit Characteristics

Туре	No. of units	Capacity (MW)
Nuclear	2	4,499
Gas	94	20,595.6
Coal	6	285.9
Oil	5	252
Dual fuel	23	4,599
Import	22	12,691
Hydro	6	10,842
Biomass	3	558
Geothermal	2	1,193
Wind (deep)	10	14,143
Fast thermal	88	11,006.1
Slow thermal	42	19,225.4

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Model	Gens	Buses	Lines	Hours	Scens.
CAISO1000	130	225	375	24	1000
WILMAR	45	N/A	N/A	36	6
PJM	1011	13867	18824	24	1

Model	Integer var.	Cont. var.	Constraints
CAISO1000	3,121,800	20,643,120	66,936,000
WILMAR	16,000	151,000	179,000
PJM	24,264	833,112	1,930,776

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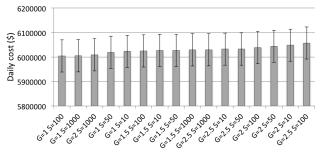
Number of Scenarios Versus Optimality Gap

• A large number of scenarios:

- results in a more accurate representation of uncertainty
- increases the amount of time required in each iteration of the subgradient algorithm
- A smaller optimality gap implies that the relaxation is 'closer' to an optimal solution
- Given a time budget (a few hours at best in day-ahead operations), do we want to solve a more representative problem less accurately or a less representative problem more accurately?

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Cost Ranking: Winter Weekdays

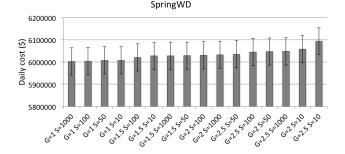


WinterWD

- S = 1000 corresponds to Shapiro's SAA algorithm
- Average daily cost and one standard deviation for 1000 Monte Carlo outcomes

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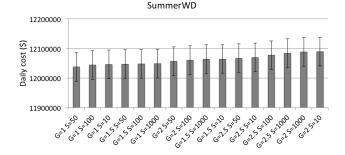
Cost Ranking: Spring Weekdays



- S = 1000 corresponds to Shapiro's SAA algorithm
- Average daily cost and one standard deviation for 1000 Monte Carlo outcomes

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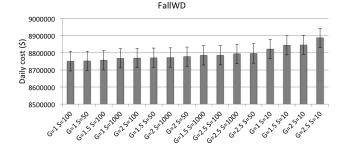
Cost Ranking: Summer Weekdays



- S = 1000 corresponds to Shapiro's SAA algorithm
- Average daily cost and one standard deviation for 1000 Monte Carlo outcomes

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Cost Ranking: Fall Weekdays



- S = 1000 corresponds to Shapiro's SAA algorithm
- Average daily cost and one standard deviation for 1000 Monte Carlo outcomes

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Influence of Duality Gap

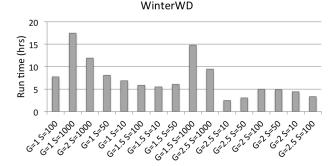
- Among three worse policies in summer, S = 1000 with G = 2%, 2.5%
- Best policy for all day types has a 1% optimality gap (S = 1000 only for spring)
- For all but one day type the worst policy has G = 2.5%
- For spring, best policy is G = 1, S = 1000
- For spring, summer and fall the worst policy is the one with the fewest scenarios and the greatest gap, namely G = 2.5, S = 10

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Validation of Scenario Selection Policy

- Top performance for winter, summer and fall is attained by proposed scenario selection algorithm based on importance sampling
- For all day types, the importance sampling algorithm results in a policy that is within the top 2 performers
- Satisfactory performance (within top 3) can be attained by models of moderate scale (S50), provided an appropriate scenario selection policy is utilized

Run Time Ranking: Winter Weekdays

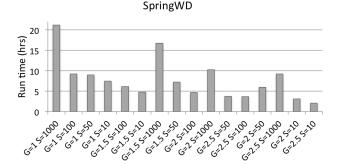


• Best-case running times (S = P)

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Run Time Ranking: Spring Weekdays



• Best-case running times (S = P)

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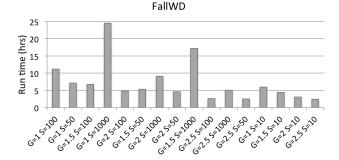
Run Time Ranking: Summer Weekdays

SummerWD

• Best-case running times (S = P)

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Run Time Ranking: Fall Weekdays



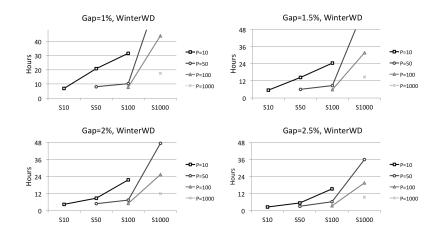
• Best-case running times (S = P)

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How Many Scenarios?

- Depends on the amount of available computation time and the number of available computational resources
- No theoretical guarantee that a smaller gap for the same instance will deliver a better result (compare, for example, the case of G = 2 with the case of G = 2.5 for S = 10 for winter weekdays). Nevertheless, it is commonly preferable to decrease the duality gap as much as possible

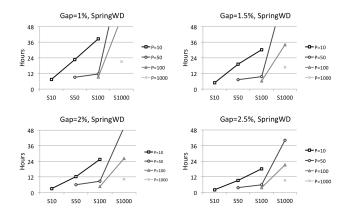
Running Times: Winter Weekdays



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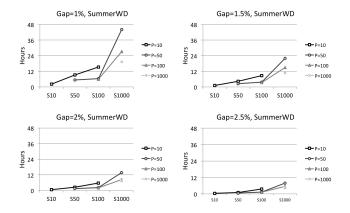
Running Times: Spring Weekdays



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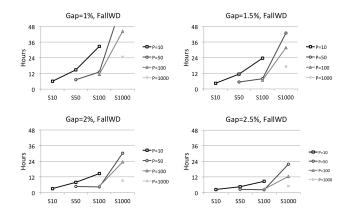
Running Times: Summer Weekdays



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Running Times: Fall Weekdays



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Unit Commitment: Winter Weekdays

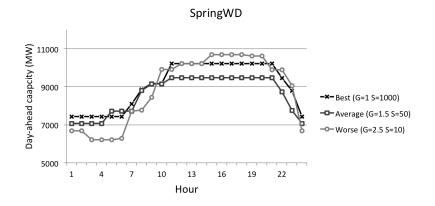
Day-ahead caapcity (MW) 11000 -×-Best (G=1 S=100) 9000 -D-Average (G=1.5 S=50) ----- Worse (G=2.5 S=100) ×-D-7000 7 10 13 16 19 22 1 Δ Hour

WinterWD

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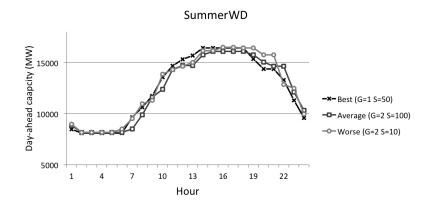
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Unit Commitment: Spring Weekdays



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Unit Commitment: Summer Weekdays



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Unit Commitment: Fall Weekdays

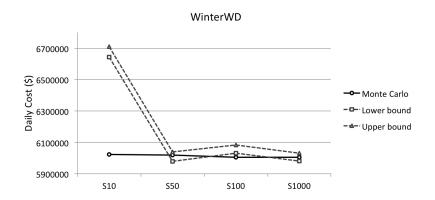
13000 -x-x-x-Day-ahead caapcity (MW) 11000 -×-Best (G=1 S=100) -D-Average (G=2 S=50) 9000 -O-Worse (G=2.5 S=10) x-x-x-• 7000 19 22 1 4 7 10 13 16 Hour

FallWD

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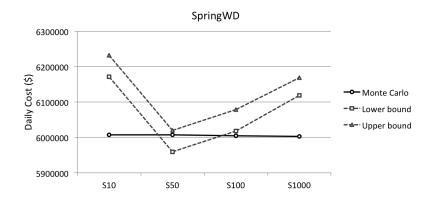
Bounds: Winter Weekdays



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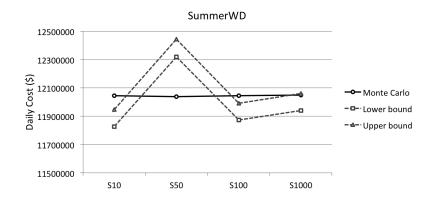
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Bounds: Spring Weekdays



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Bounds: Summer Weekdays

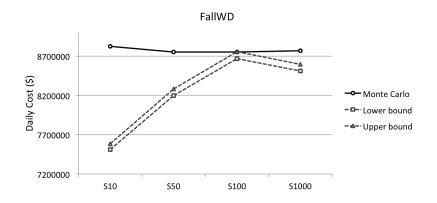


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Bounds: Fall Weekdays



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Conclusions

- Validation of scenario selection algorithm: The importance sampling scenario selection algorithm performs favorably relative to SAA with 1000 scenarios
- Decreasing the duality gap versus increasing the number of scenarios: Reducing the duality gap seems to yield comparable benefits relative to adding more scenarios
- Efficiency gains: All problems solved within 24 hours, given enough processors. Parallelization permits the running time of the studied model to run within acceptable time frames from operations standpoint.

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Perspectives

- Extensions of present model
 - Bundling methods and asynchronous multiplier updating
 - Analysis of duality gap
 - Comparison of alternative relaxations
- Parallel algorithms for fast topology control (ARPA-E)
- Comparative study of Lagrangian relaxation and Benders decomposition algorithms for stochastic unit commitment and security constrained unit commitment

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References

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- A. Papavasiliou, S. S. Oren, R. P. O'Neill, *Reserve Requirements for Wind Power Integration: A Scenario-Based Stochastic Programming Framework, IEEE Transactions on Power Systems*, Vol. 26, No. 4, November 2011.
- A. Papavasiliou, S. S. Oren, B. Rountree, *Applying High Performance Computing to Multi-Area Stochastic Unit Commitment for Renewable Penetration.*

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Questions?

Contact: anthony.papavasiliou@uclouvain.be

http://perso.uclouvain.be/anthony.papavasiliou/public_html/

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